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Robotic Monitoring of Power Systems | Seminar Report, PPT

Distributed computing is a field of computer science that studies distributed systems. A distributed system is a system whose components are located on different networked computers, which then communicate and coordinate their actions by passing messages to one another. The components interact with one another in order to achieve a common goal.

Distributed computing - Wikipedia

A self-driving car, also known as a robot car, autonomous car, auto, or driverless car, is a vehicle that is capable of sensing its environment and moving with little or no human input.. Autonomous cars combine a variety of sensors to perceive their surroundings, such as radar, computer vision, Lidar, sonar, GPS, odometry and inertial measurement units.

Self-driving car - Wikipedia

2.1. Practical considerations. One of the main practical considerations is the weight of the soft robotic glove. Aubin et al. determined that weight of such a device mounted on a hand should not exceed 0.5 kg .Any additional components of the system required for power, actuation or control can be distributed around the waist or the back and should weigh no more than 3 kg, which is the typical ...

Soft robotic glove for combined assistance and at-home

In a leap for robotic development, the MIT researchers who built a robotic cheetah have now trained it to see and jump over hurdles as it runs " making this the first four-legged robot to run ...

Massachusetts Institute of Technology (MIT) - YouTube

Background and update on BOIDS, the 1987 model of group motion in flocks, herds, schools and related phenomena. Includes a Java-based demonstration and many links to related research and applications.

Boids (Flocks, Herds, and Schools: a Distributed

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Bulletin of the World Health Organization | November 2004, 82 (11) 867 Abstract This paper explores the debate and initiatives concerning the use of information technology (IT) in primary health care in

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